Partition-of-unity localizations of dual-weighted residual estimators for single and multiple goal functionals

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In this talk, we present our efforts over the last years to apply partition-of-unity localizations in a posteriori goal-oriented error control and adaptivity for stationary and nonstationary problems. The partition-of-unity greatly facilitates error localization for nonlinear problems, coupled problems, multiphysics applications, up to space-time coupled variational inequality systems. We discuss the idea, concepts and show several applications in single and multigoal-oriented error estimation.

References:

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